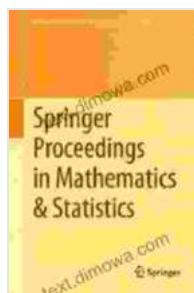


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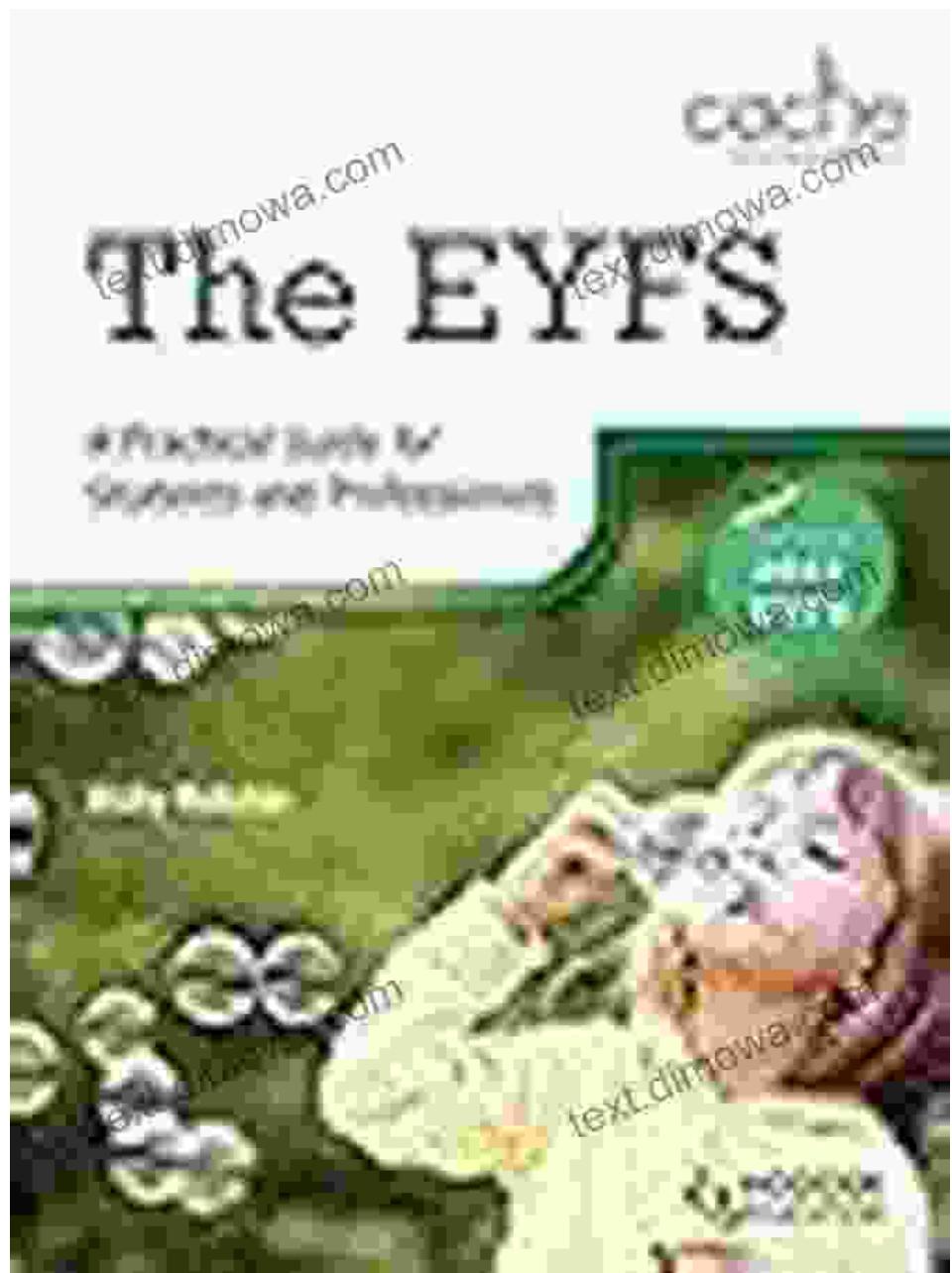
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Example Image 1:

Separable Differential Equation



$$\frac{dy}{dx} = f(x) g(y)$$

$$\Rightarrow \frac{dy}{g(y)} = f(x) dx$$

$$\Rightarrow \int \frac{1}{g(y)} dy = \int f(x) dx$$

Example Image 2:

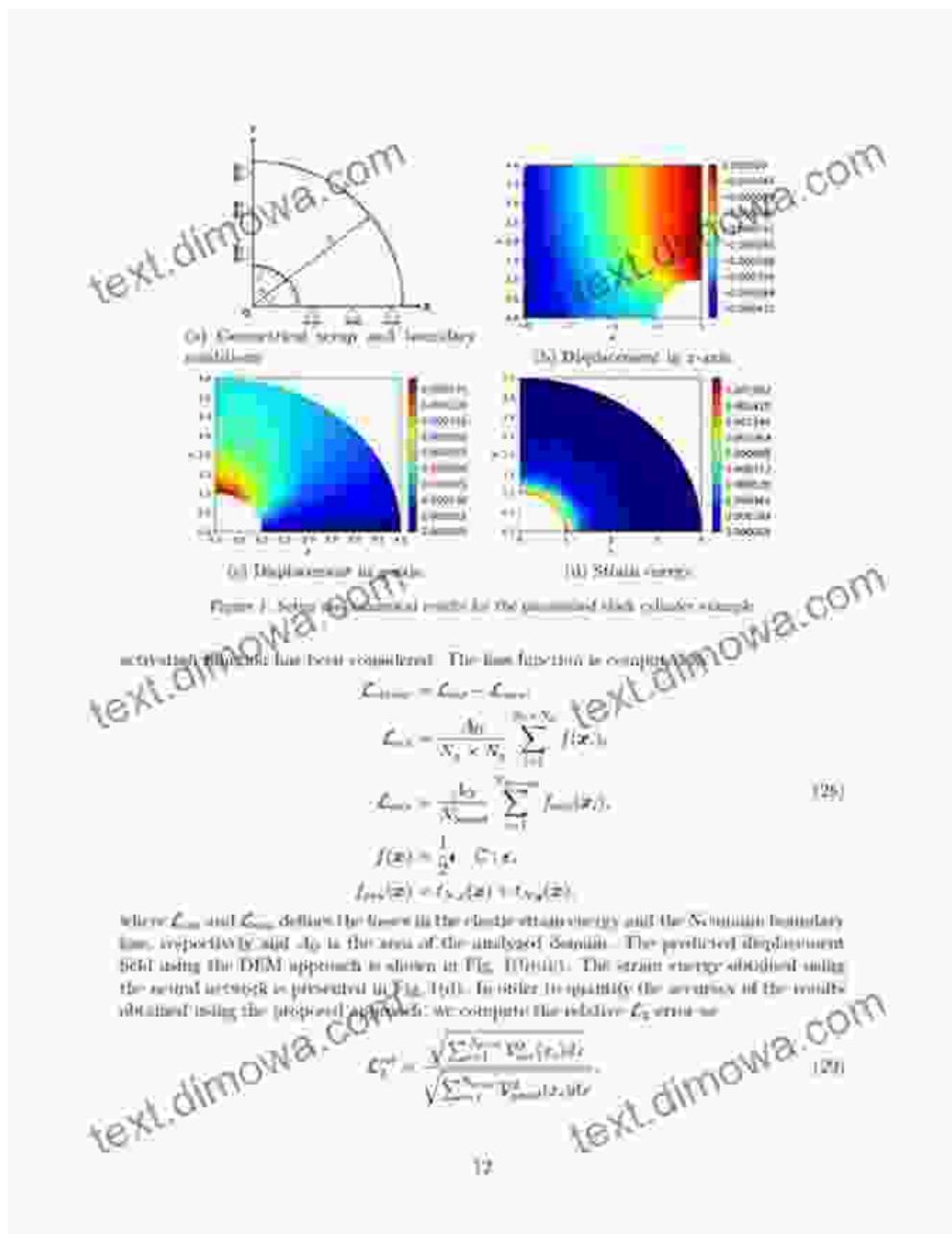


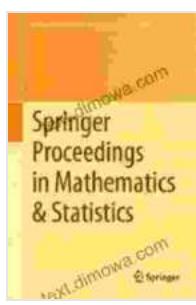
Figure 1 Solving the inverse problem for the quartered thick cylinder example

activation functions have been considered. The loss function is computed as

$$\begin{aligned} \mathcal{L}_{\text{loss}} &= \mathcal{L}_{\text{dis}} + \mathcal{L}_{\text{ene}} \\ \mathcal{L}_{\text{dis}} &= \frac{A_0}{N_d \times N_d} \sum_{i=1}^{N_d \times N_d} f(\mathbf{x}_i), \\ \mathcal{L}_{\text{ene}} &= \frac{b_0}{N_s} \sum_{i=1}^{N_s} f_{\text{ene}}(\mathbf{x}_i), \\ f(\mathbf{x}) &= \frac{1}{2} \mathbf{x}^\top \mathbf{C}(\mathbf{x}), \\ f_{\text{ene}}(\mathbf{x}) &= f_{\text{dis}}(\mathbf{x}) + f_{\text{ene}}(\mathbf{x}), \end{aligned} \quad (26)$$

where \mathcal{L}_{dis} and \mathcal{L}_{ene} define the losses in the elastic strain energy and the Neumann boundary loss, respectively, and A_0 is the area of the analyzed domain. The predicted displacement field using the DSEM approach is shown in Fig. 1(b)(iii). The strain energy obtained using the neural network is presented in Fig. 1(d). In order to quantify the accuracy of the results obtained using the proposed approach, we compute the relative L_2 error as

$$E_r^{\text{rel}} = \frac{\sqrt{\sum_{i=1}^{N_s} \mathbf{v}_{\text{true}}^T(\mathbf{x}_i) \mathbf{v}_{\text{pred}}(\mathbf{x}_i)}}{\sqrt{\sum_{i=1}^{N_s} \mathbf{v}_{\text{true}}^T(\mathbf{x}_i) \mathbf{v}_{\text{true}}(\mathbf{x}_i)}}. \quad (27)$$

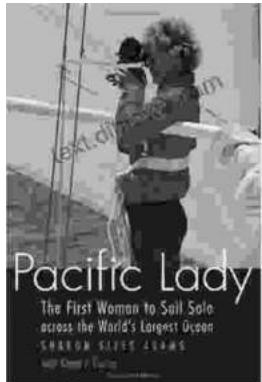


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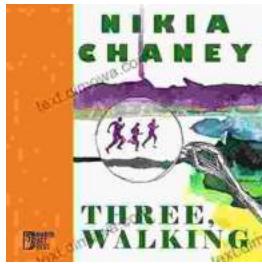
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